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DESIGN,OPTIMIZATION AND ANALYSIS OF ROCKER-BOGIE STAIR CLIMBING ROBOT



Design, Optimization and
Analysis of Rocker-Bogie
Stair Climbing Robot
Using Taguchi Method and ANSYS Rigid Dynamics



Condition: New. Publisher/Verlag: LAP Lambert Academic Publishing | Using Taguchi Method and ANSYS Rigid Dynamics | In recent years, many robotic platforms have been designed for structure and uneven terrains to carry out military, defense and Intelligence operations. But it is difficult to operate them in structured terrain especially when dimension of stairs are changing from place to place as per building and construction norms. If we work on this limitation of robotic platform to climb against variable dimensions of...

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